A 3D Computational Torso Model for Electrocardiology

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Computed tomography was used to image 99 serial cross-sectional slices spanning from neck to abdomen of the porcine torso (1 mm thick, 5 mm spacing). Boundaries between the various organs and tissue layers were identified for surface digitisation as shown for slice 20.

Cardiac and Body Surface Potential Mapping





Abstract

ance of heart rhythm is thought to account for around one third Disturbance of heart rhythms in knoght to account for around one high of all deaths in high Vestmen Weirk. If the elemencatingpum (EUG) is of cardiac electrical activity. However, because of the limited mumber of recording isses (sums) 212 and its primitive hererical basis, the EUG has seen list development and remains somewhat subjective. With the about of new power data comparisonal techniques, it is now theoreticall prossible to accounted the detailed electrical activity alth enour arafice of the heart alde array of body surface recordings (the inverse problem of rocardiography'). At this stage, the accuracy of these computer generated cardiac maps is unknown in-vivo. electrocar

We have recently acquired a series of cross-sectional CT images and We have recently acquired a series of cross-scional CT images and developed an anticular log accurate computational model of the parcite tors and its constituents using a non-linear optimisation procedure on OSCAR. We have also concided antimaticents in vivo electrophotential developed anticellular anticellular anticellular anticellular transformed the heart. Exercical events have been interpreted and visualized single or parcine model (or two signals) and missing an existing 3D antonico- computational model of the varicke (heart signals). We propose to use the deal and to validate the use of new electrical imaging techniques developed by the Oxford Ax land groups modeling and body surface potential mapping can be shown to considerable indical interest is a non invite variant disjective muss accuniterable indical interest is a non invite variant disjective muss accuniterable indical interest is a non invite variant disjective muss accuniterable indical interest is a non invite variant disjective muss accuniterable indical interest is a non invite variant disjective muss accuniterable indical interest is a non interview to addisjective muss accuniterable indical interview and disjective muss



Development of the Computational Torso Model

Fitted porcine heart and lungs



For each anatomical surface (endocardium, epicardium, lungs, fat and torso), 3D data sets were created by combining the appropriate digitised data coordinates across all CT slices. A non-linear optimisation procedure, which incorporated non-linear constraints and smoothing, was used to obtain a parametric representation of each surface in 3D space. C1 cubic Hermite elements were used to define the smoothly continuous anatomical geometry. Full details of the fitting procedure may be found in Bradley et al, Annals of Biomed Eng. 25:96-111, 1997. Approximately 2-10 hours of CPU time were required to fit each surface and the finite element nature of the computations permitted parts of this procedure to be parallelised in a coarse-grained manner. Fitted surfaces for the lungs, epicardium and outer torso (skin) surface are shown above. The table details the numbers of finite element nodes and elements used to define the various surfaces.

Region	Nodes	Elements
Epicardium	102	112
LV Endocardium	27	30
RV Endocardium	38	42
Left Lung	74	80
Right Lung	74	80
Outer Torso	439	464
TOTAL	754	808



3D Anatomical Electropotential Maps



The dense array of body surface ECG recordings were visualised during peak ORS by fitting a scalar electropotential field onto the outer surface of the computational torso model. A number of anatomical landmarks were located using a FARO mechanical digitiser and incorporated into a non-linear procedure to customise the generic porcine mesh to the experimental porcine model. Anatomical locations of the torso electrodes were also digitised and the 3D positions were orthogonally projected onto the experimental mesh. The recorded ECG signals were then used to fit a continuous field, for which blue and red depict regions of negative and positive electronotential. respectively. For a full animation of the time-varying electropotential field refer to http://ww.dwsiol.cx.ac.uk/-dip/ and follow the link to our Electrocardiac Mapping web site



Objective: 3D Cardiac Electrical Activity



Anterior Posterior view view

The epicardial activation map recorded in-vivo (invasively) during one experiment has been

superimposed onto an anatomically accurate model of the cardiac ventricles (LV/RV: left/right ventricle; LAD/PDA: left anterior/posterior descending coronary artery). Red (*) and blue (o) highlight regions of earliest and latest epicardial activation, respectively. For details of this work refer to Nash et al., J Physiol, 513.P:162P, 1998, Nash et al., J Physiol, 507.P:60P, 1998 and Nash et al., J Appl Physiol, (accepted for publication) 2000. The main goal of this work is the ability to non-invasively and objectively image the electrical state of the heart. With the advent of new powerful mathematical techniques together with recent advances in high performance computing power, it is now possible to produce epicardial activation or potential maps from densely sampled ECG recordings. What is unknown at this stage is the accuracy of these computational techniques in-viv Simultaneous electropotential recordings from the torso and epicardial surface, together with detailed measurements of anatomical geometry and electrode locations will be used to quantitatively validate the performance of the new electrocardiac imaging technique



The Inverse Problem of Electrocardiography

ectrical state of the heart electropotential field at the body surface is of considerable medical interest. The inverse problem of electrocardiography is a general name that encapsulates all methods that attempt to compute the time-varying (*t*) transmembrane potential field, $\phi_{ab}(x,t)$, on the outer surface of the heart (denoted x) from extracellular potential measurements, $\phi(y,t)$, at remote locations on the body surface (denoted y).

copic sense, the relationship between the electropotential field and its current sources is well understood, via the bidomain field equation:

 $-\nabla \cdot [(\mathbf{G}_{i}(x) + \mathbf{G}_{i}(x)) \nabla \phi(x,t)] = \nabla \cdot [\mathbf{G}_{i}(x) \nabla \phi_{ii}(x,t)]$

 $(x_1,y_2) \in \mathsf{Sec}^{(n)} \cap \mathsf{Sec}^{(n)}$ where $G_k(t)$ and $G_k(t)$ are the intra- and extracellular conductivity tensors, respectively. Two meaningful approaches for solving the inverse problem will be quantitatively validated

Epicardial Potential Imaging Laplace's equation, with boundary conditions given by the vanishing of the normal component of current density on the body surface and the unknown epicardial potentials. The

result is a linear relationship between the body surface and epix andial potentials. The full approach is given in Greenvile *et al.*, *IEEE Trans Biomed Eng*, **45**:1-7, 1998. Myocardial Surface Activation Imaging

This approach first produces a series of signals at every myocardial surface point in the mesh, which are used to identify epicardial breakthrough sites. The next stage is a computationally intensive optimisation procedure to determine the full myocardial surface activation sequence. The full approach is given in Huiskamp et al., *IEEE Trans Biomed Eng*, **44**:433-446 1997

These algorithms have been implemented into a general bioengineering code called CMISS (http://www.esc.audclard.ac.nz/daupa/Bioongineering/OESS/) using finite element and boundary element techniques, which have benn parallelised in a coarse-grained manner. It remains to verify their accuracy and performace using in-vivo data.